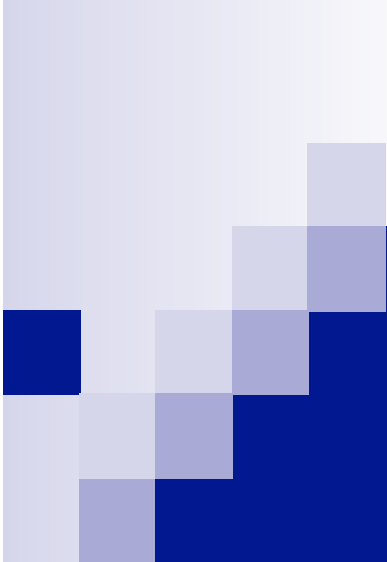




Generalized Semi-Markov Processes (GSMP)

Summary



- Some Definitions
- The Poisson Process
- Properties of the Poisson Process
 - Interarrival times
 - Memoryless property and the residual lifetime paradox
 - Superposition of Poisson processes
- Markov and Semi-Markov Processes

Probability Space and Random Variables

■ Probability Space: (Ω, F, P)

- Ω : **Sample space**: All possible outcomes of a random experiment
- F : **Event space**: A collection of subsets of Ω for which the following properties should hold.
 - If an event $A \in F$, then the complement of A , $A^c \in F$
 - If two or more events are in F , then their union should also be in F .
- P : **Probability**: A mapping from the event space to a real number $[0,1]$ which describes the likelihood that the event will occur.

■ Random Variable $X(\omega)$

- A mapping from Ω to the set of real numbers

■ Example random experiment: toss a coin

- $\Omega: \{H, T\}$, $F: \{\emptyset, H, T, \Omega\}$, $P: P[H], P[T]$
- $X(T) = 0, X(H) = 1$

Random Process

- Let (Ω, F, P) be a probability space. A stochastic (or random) process $\{X(t)\}$ is a collection of random variables defined on (Ω, F, P) , indexed by $t \in T$ (where t is usually time). $X(t)$ is the state of the process.

■ Continuous Time and Discrete Time stochastic processes

- If the set T is finite or countable then $\{X(t)\}$ is called *discrete-time process*. In this case $t \in \{0, 1, 2, \dots\}$ and we may refer to a **stochastic sequence**. We may also use the notation $\{X_k\}$, $k=0,1,2,\dots$
- Otherwise, the process is called *continuous-time process*

■ Continuous State and Discrete State stochastic processes

- If $\{X(t)\}$ is defined over a countable set, then the process is **discrete-state**, also referred to as **chain**.
- Otherwise, the process is **continuous-state**.

Classification of Random Processes

- Joint cdf of the random variables $X(t_0), \dots, X(t_n)$

$$F_X(x_0, \dots, x_n; t_0, \dots, t_n) = \Pr\{X(t_0) \leq x_0, \dots, X(t_n) \leq x_n\}$$

- Independent Process

- Let $X_1, \dots, X_n$ be a sequence of independent random variables, then

$$F_X(x_0, \dots, x_n; t_0, \dots, t_n) = F_{X_0}(x_0; t_0) \times \dots \times F_{X_n}(x_n; t_n)$$

- Stationary Process (strict sense stationarity)

- The sequence $\{X_n\}$ is stationary if and only if for any $\tau \in R$

$$F_X(x_0, \dots, x_n; t_0 + \tau, \dots, t_n + \tau) = F_X(x_0, \dots, x_n; t_0, \dots, t_n)$$

Classification of Random Processes

- Wide-sense Stationarity

- Let C be a constant and $g(\tau)$ a function of τ but not of t , then a process is wide-sense stationary if and only if

$$E\{X(t)\} = C \quad \text{and} \quad E\{X(t) \cdot X(t + \tau)\} = g(\tau)$$

- Markov Process

- The future of a process does not depend on its past, only on its present

$$\begin{aligned} \Pr\{X(t_{k+1}) \leq x_{k+1} \mid X(t_k) = x_k, \dots, X(t_0) = x_0\} \\ = \Pr\{X(t_{k+1}) \leq x_{k+1} \mid X(t_k) = x_k\} \end{aligned}$$

- Also referred to as the **Markov** property

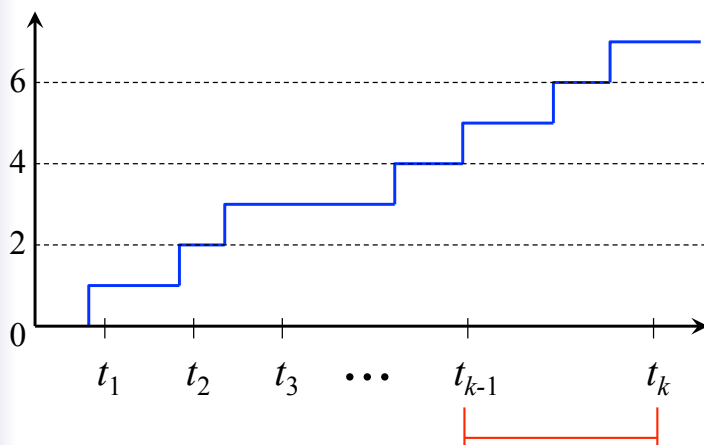
Renewal Process

- A renewal process is a chain $\{N(t)\}$ with state space $\{0,1,2,\dots\}$ whose purpose is to count state transitions. The time intervals between state transitions are assumed iid from an arbitrary distribution. Therefore, for any $0 \leq t_1 \leq \dots \leq t_k \leq \dots$

$$N(0) = 0 \leq N(t_1) \leq N(t_2) \leq \dots \leq N(t_k) \leq \dots$$

The Poisson Counting Process

- Let the process $\{N(t)\}$ which counts the number of events that have occurred in the interval $[0,t)$. For any $0 \leq t_1 \leq \dots \leq t_k \leq \dots$ $N(0) = 0 \leq N(t_1) \leq N(t_2) \leq \dots \leq N(t_k) \leq \dots$



$$N(t_{k-1}, t_k) = N(t_k) - N(t_{k-1})$$

- Process with **independent increments**: The random variables $N(t_1), N(t_1, t_2), \dots, N(t_{k-1}, t_k), \dots$ are mutually independent.
- Process with **stationary independent increments**: The random variable $N(t_{k-1}, t_k)$, does not depend on t_{k-1}, t_k but only on $t_k - t_{k-1}$

The Poisson Counting Process

Assumptions:

- At **most one event** can occur at any time instant (no two or more events can occur at the same time)
- A process with **stationary independent increments**

$$\Pr\{N(t_{k-1}, t_k) = n\} = \Pr\{N(t_k - t_{k-1}) = n\}$$

- Given that a process satisfies the above assumptions, find

$$P_n(t) \equiv \Pr\{N(t) = n\}, n = 0, 1, 2, \dots$$

The Poisson Process

- **Step 1:** Determine

$$P_0(t) \equiv \Pr\{N(t) = 0\}$$

- Starting from

$$\Pr\{N(t+s) = 0\} = \Pr\{N(t) = 0 \text{ and } N(t, t+s) = 0\}$$

Stationary independent increments

$$= \Pr\{N(t) = 0\} \Pr\{N(s) = 0\}$$

$$\Rightarrow P_0(t+s) = P_0(t) P_0(s)$$

- **Lemma:** Let $g(t)$ be a differentiable function for all $t \geq 0$ such that $g(0)=1$ and $g(t) \leq 1$ for all $t > 0$. Then for any $t, s \geq 0$

$$g(t+s) = g(t) g(s) \Leftrightarrow g(t) = e^{-\lambda t} \quad \text{for some } \lambda > 0$$

The Poisson Process

- Therefore

$$P_0(t) \equiv \Pr\{N(t) = 0\} = e^{-\lambda t}$$

- **Step 2:** Determine $P_0(\Delta t)$ for a small Δt .

$$\begin{aligned}\Pr\{N(\Delta t) = 0\} &= e^{-\lambda \Delta t} = 1 - \lambda \Delta t + \frac{(\lambda \Delta t)^2}{2!} - \frac{(\lambda \Delta t)^3}{3!} + \dots \\ &= 1 - \lambda \Delta t + o(\Delta t).\end{aligned}$$

- **Step 3:** Determine $P_n(\Delta t)$ for a small Δt .
- For $n=2,3,\dots$ since by assumption **no two events can occur at the same time**

$$P_n(\Delta t) \equiv \Pr\{N(\Delta t) = n\} = o(\Delta t)$$

- As a result, for $n=1$

$$P_1(\Delta t) \equiv \Pr\{N(\Delta t) = 1\} = \lambda \Delta t + o(\Delta t)$$

The Poisson Process

- **Step 4:** Determine $P_n(t+\Delta t)$ for any n

$$\begin{aligned}P_n(t+\Delta t) &\equiv \Pr\{N(t+\Delta t) = n\} = \sum_{k=0}^n P_{n-k}(t) P_k(\Delta t) \\ &= P_n(t) P_0(\Delta t) + P_{n-1}(t) P_1(\Delta t) + o(\Delta t). \\ &= [1 - \lambda \Delta t + o(\Delta t)] P_n(t) + [\lambda \Delta t + o(\Delta t)] P_{n-1}(t) + o(\Delta t).\end{aligned}$$

- Moving terms between sides,

$$\frac{P_n(t+\Delta t) - P_n(t)}{\Delta t} = -\lambda P_n(t) + \lambda P_{n-1}(t) + \frac{o(\Delta t)}{\Delta t}.$$

- Taking the limit as $\Delta t \rightarrow 0$

$$\frac{dP_n(t)}{dt} = -\lambda P_n(t) + \lambda P_{n-1}(t)$$

The Poisson Process

- **Step 5:** Solve the differential equation to obtain

$$P_n(t) \equiv \Pr\{N(t) = n\} = \frac{(\lambda t)^n}{n!} e^{-\lambda t}, \quad t \geq 0, \quad n = 0, 1, 2, \dots$$

- This expression is known as the **Poisson distribution** and it fully characterizes the stochastic process $\{N(t)\}$ in $[0, t)$ under the assumptions that
 - No two events can occur at exactly the same time, and
 - Independent stationary increments
- You should verify that

$$E[N(t)] = \lambda t \quad \text{and} \quad \text{var}[N(t)] = \lambda t$$
- Parameter λ has the interpretation of the “**rate**” that events arrive.

Properties of the Poisson Process: Intervent Times

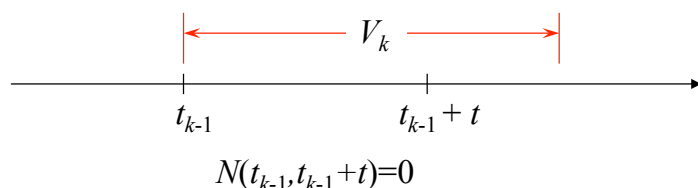
- Let t_{k-1} be the time when the $k-1$ event has occurred and let V_k denote the (random variable) interevent time between the k th and $k-1$ events.
- What is the cdf of V_k , $G_k(t)$?

$$\begin{aligned} G_k(t) &= \Pr\{V_k \leq t\} = 1 - \Pr\{V_k > t\} \\ &= 1 - \Pr\{0 \text{ arrivals in the interval } [t_{k-1}, t_{k-1} + t)\} \\ &= 1 - \Pr\{N(t) = 0\} \\ &= 1 - e^{-\lambda t} \end{aligned}$$

Stationary independent increments

$$\Rightarrow G(t) = 1 - e^{-\lambda t}$$

Exponential Distribution



Properties of the Poisson Process: Exponential Interevent Times

- The process $\{V_k\}$ $k=1,2,\dots$, that corresponds to the interevent times of a Poisson process is an iid stochastic sequence with cdf

$$G(t) = \Pr\{V_k \leq t\} = 1 - e^{-\lambda t}$$

- The corresponding pdf is

$$g(t) = \lambda e^{-\lambda t}, \quad t \geq 0$$

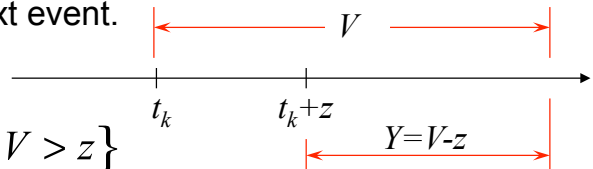
Therefore, the Poisson is also a **renewal** process

- One can easily show that

$$E[V_k] = \frac{1}{\lambda} \quad \text{and} \quad \text{var}[V_k] = \frac{1}{\lambda^2}$$

Properties of the Poisson Process: Memoryless Property

- Let t_k be the time when the previous event has occurred and let V denote the time until the next event.
- Assuming that we have been at the current state for z time units, let Y be the remaining time until the next event.
- What is the cdf of Y ?



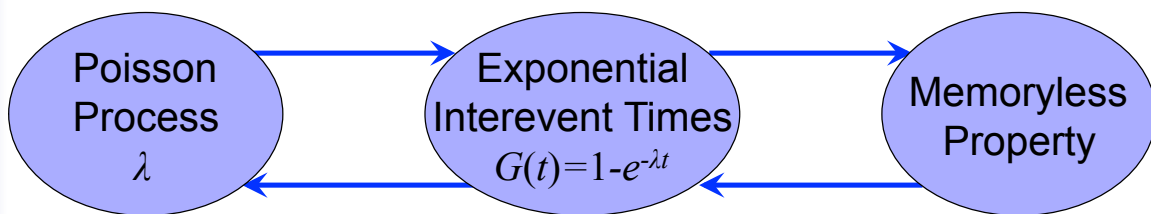
$$\begin{aligned} F_Y(t) &= \Pr\{Y \leq t\} = \Pr\{V - z < t \mid V > z\} \\ &= \frac{\Pr\{V > z \text{ and } V < z + t\}}{\Pr\{V > z\}} = \frac{\Pr\{z < V < z + t\}}{1 - \Pr\{V < z\}} \\ &= \frac{G(t+z) - G(z)}{1 - G(z)} = \frac{1 - e^{-\lambda(t+z)} - 1 + e^{-\lambda z}}{1 - 1 + e^{-\lambda z}} \end{aligned}$$

$\Rightarrow F_Y(t) = 1 - e^{-\lambda t} = G(t)$ **Memoryless!** It does not matter that we have already spent z time units at the current state.

Memoryless Property

- This is a **unique** property of the exponential distribution. If a process has the memoryless property, then it must be exponential, i.e.,

$$\Pr\{V \leq z+t \mid V > z\} = \Pr\{V \leq t\} \Leftrightarrow \Pr\{V \leq t\} = 1 - e^{-\lambda t}$$

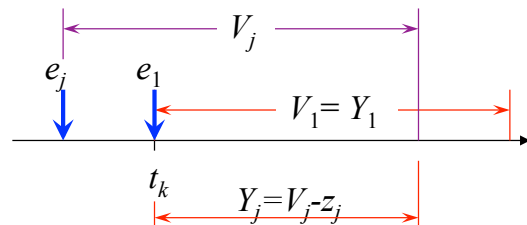


Superposition of Poisson Processes

- Consider a DES with m events each modeled as a Poisson Process with rate λ_i , $i=1, \dots, m$. What is the resulting process?
- Suppose at time t_k we observe event 1. Let Y_1 be the time until the next event 1. Its cdf is $G_1(t) = 1 - \exp\{-\lambda_1 t\}$.
- Let $Y_2, \dots, Y_m$ denote the residual time until the next occurrence of the corresponding event.
- Their cdfs are:

Memoryless Property

$$G_i(t) = 1 - e^{-\lambda_i t}$$



- Let Y^* be the time until the **next event** (any type).

$$Y^* = \min \{Y_i\}$$

- Therefore, we need to find

$$G_{Y^*}(t) = \Pr\{Y^* \leq t\}$$

Superposition of Poisson Processes

$$\begin{aligned}
 G_{Y^*}(t) &= \Pr\{Y^* \leq t\} = \Pr\{\min\{Y_i\} \leq t\} \\
 &= 1 - \Pr\{\min\{Y_i\} > t\} \\
 &= 1 - \Pr\{Y_1 > t, \dots, Y_m > t\} \\
 &= 1 - \prod_{i=1}^m \Pr\{Y_i > t\} = 1 - \prod_{i=1}^m e^{-\lambda_i t}
 \end{aligned}$$

Independence

$$\Rightarrow G_{Y^*}(t) = 1 - e^{-\Lambda t} \quad \text{where} \quad \Lambda = \sum_{i=1}^m \lambda_i$$

- The superposition of m Poisson processes is **also a Poisson process** with rate equal to the sum of the rates of the individual processes

Superposition of Poisson Processes

- Suppose that at time t_k an event has occurred. What is the probability that the next event to occur is event j ?
- Without loss of generality, let $j=1$ and define

$$Y' = \min\{Y_i: i=2, \dots, m\}. \quad 1 - \exp\left\{-\sum_{i=2}^m \lambda_i t\right\} = 1 - \exp\{-\Lambda' t\}$$

$$\Pr\{\text{next event is } j=1\} = \Pr\{Y_1 \leq Y'\} =$$

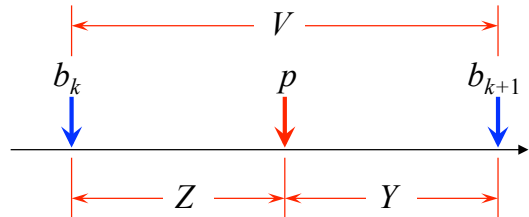
$$= \int_0^\infty \int_0^{y'} \lambda_1 e^{-\lambda_1 y_1} \Lambda' e^{-\Lambda' y'} dy_1 dy'$$

$$= \int_0^\infty \Lambda' (1 - e^{-\lambda_1 y_1}) e^{-\Lambda' y'} dy'$$

$$= \frac{\lambda_1}{\Lambda} \quad \text{where} \quad \Lambda = \sum_{i=1}^m \lambda_i$$

Residual Lifetime Paradox

- Suppose that buses pass by the bus station according to a Poisson process with rate λ . A passenger arrives at the bus station at some random point.



- How long does the passenger has to wait?

■ Solution 1:

- $E[V] = 1/\lambda$. Therefore, since the passenger will (on average) arrive in the middle of the interval, he has to wait for $E[Y] = E[V]/2 = 1/(2\lambda)$.
- But using the memoryless property, the time until the next bus is exponentially distributed with rate λ , therefore $E[Y] = 1/\lambda$ not $1/(2\lambda)$!

■ Solution 2:

- Using the memoryless property, the time until the next bus is exponentially distributed with rate λ , therefore $E[Y] = 1/\lambda$.
- But note that $E[Z] = 1/\lambda$ therefore $E[V] = E[Z] + E[Y] = 2/\lambda$ not $1/\lambda$!

Markov and Semi-Markov Property

- The Markov Property requires that the process has no memory of the past. This **memoryless** property has two aspects:
 - All past state information is irrelevant in determining the future (**no state memory**).
 - **How long** the process has been in the current state is also irrelevant (**no state age memory**).
 - The latter implies that the lifetimes between subsequent events (interevent time) should also have the memoryless property (i.e., exponentially distributed).
- Semi-Markov Processes
 - For this class of processes the requirement that the state age is irrelevant is relaxed, therefore, the interevent time is no longer required to be exponentially distributed.

Example

- Consider the process

$$X_{k+1} = X_k - X_{k-1}$$

with $\Pr\{X_0=0\} = \Pr\{X_0=1\} = 0.5$ and $\Pr\{X_1=0\} = \Pr\{X_1=1\} = 0.5$

- Is this a Markov process? **NO**
- Is it possible to make the process Markov?
- Define $Y_k = X_{k-1}$ and form the vector $Z_k = [X_k, Y_k]^T$ then we can write

$$Z_{k+1} = \begin{bmatrix} X_{k+1} \\ Y_{k+1} \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} X_k \\ Y_k \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & 0 \end{bmatrix} Z_k$$

Generalized Semi-Markov Processes (GSMP)

- A GSMP is a stochastic process $\{X(t)\}$ with state space X generated by a stochastic timed automaton

$$(X, E, \Gamma, f, p_0, G)$$

- X is the countable **state space**
- E is the countable **event set**
- $\Gamma(x)$ is the **feasible event set** at state x .
- $f(x, e)$: is **state transition function**.
- p_0 is the probability mass function of the initial state
- G is a vector with the cdfs of all events.
- The semi-Markov property of GSMP is due to the fact that at the state transition instant, the next state is determined by the current state and the event that just occurred.