University of Cyprus Biomedical Imaging and Applied Optics



## ECE 370 Introduction to Biomedical Engineering

## **Principles of Biomechanics**

## Introduction



#### • What is Biomechanics?

- The study of internal and external forces acting on the body segments, and the effects produced by these forces.
- The principles of engineering, specifically mechanics, applied to human movement.
- Kinesiology
  - Study of movement
  - Tends to focus on neuro musculoskeletal systems

#### Problems studied by biomechanists

- 1. How can human performance be enhanced?
- 2. How can injuries be prevented?
- 3. How can rehabilitation from injury be expedited?

#### Areas of Biomechanics

- Sports Biomechanics
- Occupational Biomechanics
- Clinical Biomechanics

# **Sports Biomechanics**

- Understanding and applying mechanical concepts to
  - Assess the most optimal way to move the body
  - Achieve maximal performance
  - Minimize risk of injury





## **Occupational Biomechanics**

- Design machines and the workplace to
  - Reduce repetitive stress on workers' joints
  - Minimize injuries and long term problems



headaches





# **Clinical Biomechanics**

- Analyze the mechanics of injured patients and provide feedback (biofeedback)
  - Restore normal function.



## Isaac Newton's "3 Laws of Motion"

#### The Law of Inertia

 An object at rest tends to stay at rest and an object in motion tends to stay in motion (unless an external force is applied eg. friction or gravity).

#### The Law of Acceleration

- A force applied to a body causes an acceleration proportional to the force, in the direction of the force, and inversely proportional to the body's mass.
- F=ma

#### The Law of Reaction

• For every action there is an equal and opposite reaction.





# **Types of Motion**

- It is important to distinguish between two types of motion:
- Linear (or Translational) Motion
  - Movement in particular direction. Example: a sprinter accelerating down the track.

#### Rotational Motion

- Movement about an axis. The force does not act through the centre of mass, but rather is "off-centre," and this results in rotation. Example: ice-skater's spin.
- Most human movements are rotational ie they take place around an axis







## **Centre of Mass (Gravity)**

- The point on an object where its mass is balanced
  - The point where that body would balance on a very small base
  - A force applied through the CoM → Linear motion
  - A force applied at a distance to the CoM → Rotation or Angular motion
- Important concept when stability is important













- Seven Principles of Biomechanical Analysis
- Grouped into 4 broad categories:
  - 1. stability,
  - 2. maximum effort,
  - 3. linear motion, and
  - 4. angular motion.

## • STABILITY

## • Principle 1:

- The stability increases
  - Lower center of mass
  - Larger base of support
  - Closer the center of mass to the base of support
  - Greater mass
- Examples:
  - Sumo wrestling
  - Wrestling
  - Gymnastics
    - Is this position stable? Why?









## **Unstable Balance**

- Sometimes athletes need to be balanced but ready to move quickly i.e. unstable
- Examples
  - Sprint start
  - Receiving serve in tennis
  - Swim start
    - What makes this unstable?





#### *12*

# **Biomechanical Analysis**

- MAXIMUM EFFORT
- Principle 2:
  - The production of <u>maximum</u> <u>force</u> requires the use of all possible joint movements that contribute to the task's objective.
  - Examples:
    - Bench press
    - Sprint start







- MAXIMUM EFFORT
- Principle 3:

•

- The production of maximum velocity requires the use of joints in order
  - From largest to smallest.
- Examples:
  - Pitch a baseball
  - Hitting a golf ball



- LINEAR MOTION
- Principle 4:
  - The greater the applied impulse, the greater the increase in velocity.
    - a = F/m
    - Range of Motion (ROM) important
    - Example:
      - Spiking a volleyball





## LINEAR MOTION

## • Principle 5:

- Movement usually occurs in the direction opposite that of the applied force.
  - Affected by gravity and other forces
- Examples:
  - Basketball
  - Kicking





## ANGULAR MOTION

### • Principle 6:

- Angular motion is produced by the application of a force acting at some distance from an axis, that is, by torque.
- Torque (or moment)
  - $\tau = r \times F = |r||F|sin(\theta)$
- Example:
  - Diving







## Levers



FirstThe fulcrum lies between the effort and the resistanceLess forceLoadEffortSee saw Crowbar Hammer pulling out a nailSecondThe resistance lies between the fulcrum and the point of effortLess forceSecondThe resistance lies between the fulcrum and the point of effortLess forceEffortLoadWheelbarrow Opening a door by the handle Rowing a boatThirdThe effort lies between the resistance and the fulcrumMore force, more speedThirdThe effort lies between the resistance and the fulcrumBiceps curl Most limbs of the	Class	Illustration	Examples
LoadEffortSee saw Crowbar Hammer pulling out a nailSecondThe resistance lies between the fulcrum and the point of effortLess forceEffortLoadWheelbarrow Opening a door by the handle Rowing a boatThirdThe effort lies between the resistance and the fulcrumMore force, more speedThirdThe effort lies between the resistance and the fulcrumMore force, more speed	First	The fulcrum lies between the effort and the resistance	Less force
Class 1 LeverSecondThe resistance lies between the fulcrum and the point of effortLess forceEffortLoadWheelbarrow Opening a door by the handle Rowing a boatOpening a door by the handle Rowing a boatThirdThe effort lies between the resistance and the fulcrumMore force, more speedLoadEffortBiceps curl Most limbs of the		Effort Load Fulcrum	See saw Crowbar Hammer pulling out a nail
Second The resistance lies between the fulcrum and the point of effort Under the fulcrum and the point of effort Under the fulcrum of the handle fulcrum of the handle Rowing a boat Class 2 Lever Third The effort lies between the resistance and the fulcrum function of the fulcrum of the fulc	0	Class 1 Lever	
Effort     Load     Wheelbarrow       Fulcrum     Opening a door by the handle       Rowing a boat       Class 2 Lever   Third The effort lies between the resistance and the fulcrum Load Effort Biceps curl Most limbs of the	Second	fulcrum and the point of effort	Less force
Third     The effort lies between the resistance and the fulcrum     More force, more speed       Load     Effort     Biceps curl Most limbs of the		Effort Load	Wheelbarrow
Fulcrum     Rowing a boat       Class 2 Lever     Rowing a boat       Third     The effort lies between the resistance and the fulcrum     More force, more speed       Load     Effort     Biceps curl Most limbs of the			Opening a door by the handle
Class 2 Lever       Third     The effort lies between the resistance and the fulcrum     More force, more speed       Load     Effort     Biceps curl Most limbs of the		Fulcrum	Rowing a boat
Third     The effort lies between the resistance and the fulcrum     More force, more speed       Load     Effort     Biceps curl       Most limbs of the     Biceps curl		Class 2 Lever	
Load Effort Biceps curl Most limbs of the	Third	The effort lies between the resistance and the fulcrum	More force, more speed
Most limbs of the		Load Effort	Biceps curl
body		Fulcrum	Most limbs of the body











#### ANGULAR MOTION

- Principle 7:
  - The principle of conservation of angular momentum
    - Angular momentum is constant when an athlete or object is free in the air
    - Once an athlete is airborne, he or she will travel with constant angular momentum.

#### Linear motion

- Force moves a body
- F = ma
- If no force is applied, momentum is conserved
- p = m v

#### Angular motion

- Torque causes a body to spin
- т = F x r = l a
  - a: rotational acceleration  $(\Delta \omega / \Delta t)$
  - · I: rotational inertia, or moment of inertia
  - I ∝ m r<sup>2</sup>
- If no torque is applied, angular momentum is conserved
- $L = I \omega \propto mr^2 \omega$





## **Examples of Conservation of Momentum**

#### Ice-Skating

- The ice-skater begins to spin with arms spread apart then suddenly brings them closer to the body.
- The skater's spin (angular velocity) increases.
- Explanation
  - When a figure skater draws her arms and a leg inward, she reduces the distance between the axis of rotation and some of her mass → reduces her moment of inertia
  - Angular momentum is conserved → rotational velocity must increase to compensate.





## **Examples of Conservation of Momentum**

#### Diving

- After leaving the high diving board, the diver curls tightly and then opens up just before entering the water.
- By opening up before entry, the diver increases the moment of inertia → slows down the angular velocity.



**Examples of Conservation of Momentum** 

#### Gymnastics

 By opening up, the gymnast increases the moment of inertia (radius of rotation), thereby resulting in a decrease in angular velocity.







# **Conservation of Energy**

## • The conservation of energy principle

 Energy can never be created or destroyed, but can only be converted from one form to another





## **Elements of Kinesiology**

#### • Five Phases of a Sport Skill

- 1. Preliminary Movements
- 2. Backswing/Recovery
- 3. Force Producing Movements
- 4. Critical Instant
- 5. Follow-Through

#### Used to bring a skill down into smaller parts

- Helps coaches to detect and correct errors
- Key Points are "look fors" that coaches use to produce ideal mechanics / performance





#### **Preliminary Movements**

- Pick a Target
- Open stance
- Hold Ball with Opposite Hand
- Hold the Ball at Waist Height
- Eye on the Ball





#### **Backswing/Recovery**

- Eye on the ball
- Maintain good posture
- Large last step
- Ankle locked





#### **Force Producing Movements**

- Eye on the ball
- Maintain good posture
- Largest muscles to the smallest
- Use arm for balance
- Open the hips up





#### **Critical Instant**

- Eye on the ball
- Contact with hardest part of the foot
- Lock your kicking foot upwards
- Let ball fall below knee height
- Lock your leg





#### **Follow-Through**

- Be smooth and fluid
- Foot carries on towards target
- Eyes follow ball to target





## **Elements of Kinesiology**



- Why aren't there more robots walking on two legs?
  - Because it's REALLY difficult!!!

#### Dynamic Walking

- Hundreds of specific and well coordinated movements
- Almost all joints involved from head to toes
- Every step involves not only pushing the body forward but also keeping balance
  - When we walk, is like loosing our balance and falling forward
  - Just before loosing our balance, we put one leg forward to support our body

#### Running

It's even more difficult since there are moments when both legs are airborne!



## Honda Asimo



#### • The best biped robot